



Sylvester's Law of Inertia

Example of quadratic form: Take $\mathbb{C}^n$ with standard inner product:

$$x \mapsto \langle x, x \rangle_{\text{standard}} = \sum_{i=1}^n \overline{x_i} \cdot x_i = \sum_{i=1}^n |x_i|^2$$

Definition: Let V be an $\mathbb{F}$ -vector space ($\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$).

(1) A map $s: V \times V \rightarrow \mathbb{F}$ is called sesquilinear form if:

$$s(u, v + \lambda w) = s(u, v) + \lambda s(u, w) \quad (\text{linear in the second argument})$$

$$s(u + \lambda v, w) = s(u, w) + \overline{\lambda} s(v, w) \quad (\text{conjugate-linear in the first argument})$$

(2) A sesquilinear form is called conjugate-symmetric (or Hermitian)

$$s(u, v) = \overline{s(v, u)}$$

(3) If s is a conjugate-symmetric sesquilinear form, then

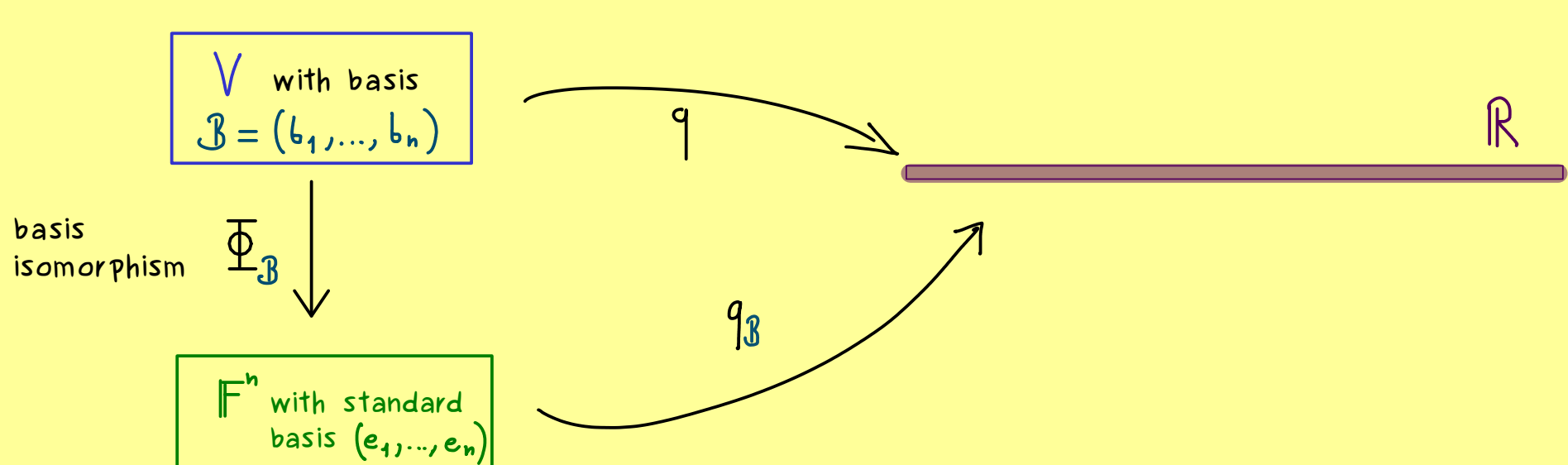
$q: V \rightarrow \mathbb{R}$, $q(v) := s(v, v)$ is called the associated quadratic form.

Polarization identity: The associated quadratic form q determines s completely:

$$s(u, v) = \frac{1}{4} (q(u+v) - q(u-v)) \quad \text{for } \mathbb{F} = \mathbb{R}$$

$$s(u, v) = \frac{1}{4} (q(u+v) - q(u-v) - i q(u+iv) + i q(u-iv)) \quad \text{for } \mathbb{F} = \mathbb{C}$$

Matrix representation of a quadratic form:



$$\begin{aligned} q_B(x) &= q(\Phi_B^{-1}\begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}) = q\left(\sum_{j=1}^n x_j \cdot b_j\right) = s\left(\sum_{i=1}^n x_i \cdot b_i, \sum_{j=1}^n x_j \cdot b_j\right) \\ &= \sum_{i=1}^n \sum_{j=1}^n \overline{x_i} \cdot x_j \underbrace{s(b_i, b_j)}_{=: a_{ij}} = \langle x, Ax \rangle_{\text{standard}} \end{aligned}$$

self-adjoint matrix $A = (a_{ij})$

Diagonalization of quadratic forms:

Let V be an $\mathbb{F}$ -vector space, s be a conjugate-symmetric sesquilinear form, and $q: V \rightarrow \mathbb{R}$ be the associated quadratic form.

Then there is a basis $\mathcal{B} = (b_1, \dots, b_n)$ such that $q_B(x) = \langle x, Ax \rangle_{\text{standard}}$

is given by a diagonal matrix:

$$A = \begin{pmatrix} \underbrace{1 \dots 1}_{r_+ \text{ times}} & & \\ & \underbrace{-1 \dots -1}_{r_- \text{ times}} & \\ & & \underbrace{0 \dots 0}_{r_0 \text{ times}} \end{pmatrix}$$

Proof: Case $q = 0$ ✓

Induction base case: $n=1$: Choose $v \in V \setminus \{0\}$ with $q(v) \neq 0$.

$$\text{Define } w := \frac{v}{\sqrt{|q(v)|}} \leadsto \mathcal{B} = (w)$$

$$\text{We get: } q(w) = s(w, w) = \frac{1}{|q(v)|} \cdot q(v) = \begin{cases} +1 \\ -1 \end{cases}$$

$$\begin{aligned} \langle x, Ax \rangle_{\text{standard}} &= q(\Phi_B^{-1}(x)) = q(x \cdot w) = \begin{cases} +|x|^2 \\ -|x|^2 \end{cases} \\ \parallel & \\ a \cdot |x|^2 &\Rightarrow a = 1 \text{ or } a = -1 \quad \checkmark \end{aligned}$$

$n-1 \rightarrow n$: Choose $v \in V \setminus \{0\}$ with $q(v) \neq 0$. $w := \frac{v}{\sqrt{|q(v)|}}$

$$\text{So } q(w) = \begin{cases} +1 \\ -1 \end{cases}$$

$$U := \{u \in U \mid s(w, u) = 0\}$$

kernel of linear map: $s(w, \cdot): V \rightarrow \mathbb{F}$
with dimension $n-1$ by rank-nullity theorem

$\Rightarrow$ there is a basis of U : $\mathcal{B} = (b_1, \dots, b_{n-1})$

such that

$$(q|_U)_B(x) = \left\langle x, \begin{pmatrix} 1 & & \\ & \ddots & \\ & & -1 & \\ & & & 0 \dots 0 \end{pmatrix} x \right\rangle_{\text{standard}}$$

Take w to extend basis to $\tilde{\mathcal{B}} = (w, b_1, \dots, b_{n-1})$ (case $q(w) = +1$)

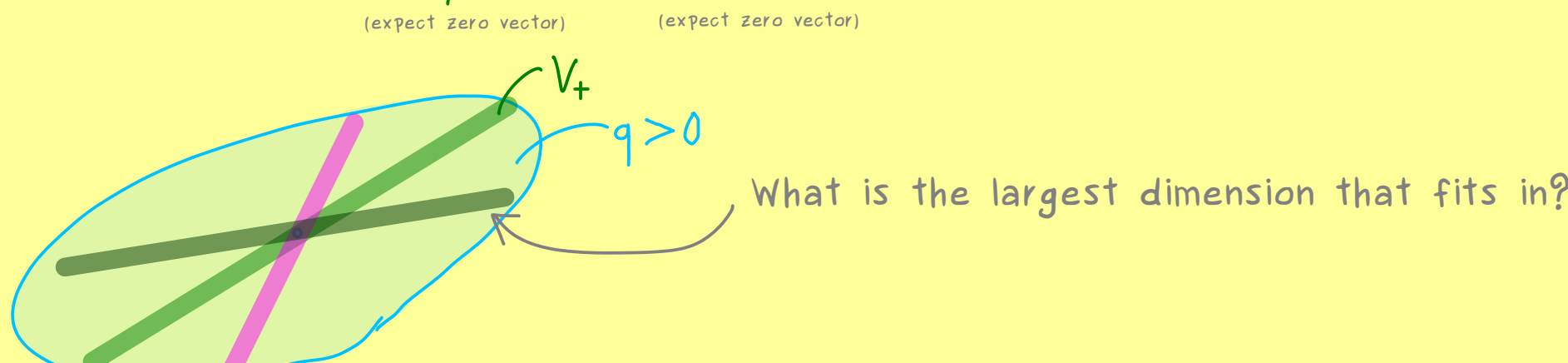
$$q_{\tilde{\mathcal{B}}}(y) = q(y_0 w + \sum_{j=1}^{n-1} y_j b_j) = s(y_0 w, y_0 w) + s\left(\sum_{i=1}^{n-1} y_i b_i, \sum_{j=1}^{n-1} y_j b_j\right)$$

$$= \begin{pmatrix} y_0 \\ \vdots \\ y_{n-1} \end{pmatrix}$$

$$= |y_0|^2 q(w) + \left\langle \begin{pmatrix} y_1 \\ \vdots \\ y_{n-1} \end{pmatrix}, \begin{pmatrix} 1 & & \\ & \ddots & \\ & & -1 & \\ & & & 0 \dots 0 \end{pmatrix} \begin{pmatrix} y_1 \\ \vdots \\ y_{n-1} \end{pmatrix} \right\rangle$$

$$= \left\langle \begin{pmatrix} y_0 \\ y_1 \\ \vdots \\ y_{n-1} \end{pmatrix}, \begin{pmatrix} +1 & & \\ & \ddots & \\ & & -1 & \\ & & & 0 \dots 0 \end{pmatrix} \begin{pmatrix} y_0 \\ y_1 \\ \vdots \\ y_{n-1} \end{pmatrix} \right\rangle_{\text{standard}} \quad \square$$

Note: The basis $(\underbrace{b_1, \dots, b_{r_+}}_{V_+, q>0}, \underbrace{b_{r_++1}, \dots, b_{r_++r_-}}_{V_-, q<0}, \underbrace{b_{r_++r_-+1}, \dots, b_n}_{V_0, q=0})$
gives subspaces: $V_+ \rightarrow q>0$, $V_- \rightarrow q<0$, $V_0 \rightarrow q=0$
(expect zero vector) (expect zero vector)



Theorem: (Sylvester's law of inertia)

The numbers r_+ , r_- , r_0 in the diagonalization are invariant:

they don't change if we choose a different basis that diagonalizes q .

Moreover: $r_+ = \max \left\{ \dim(U) \mid U \subseteq \{v \in V \mid q(v) > 0\} \cup \{0\}, U \text{ subspace of } V \right\}$

$r_- = \max \left\{ \dim(U) \mid U \subseteq \{v \in V \mid q(v) < 0\} \cup \{0\}, U \text{ subspace of } V \right\}$

Proof: Take basis $(\underbrace{b_1, \dots, b_{r_+}}_{\text{span } V_+}, \underbrace{b_{r_++1}, \dots, b_{r_++r_-}, b_{r_++r_-+1}, \dots, b_n}_{\text{span } V_- \oplus V_0})$

Now assume that there is subspace $W_+ \subseteq \{v \in V \mid q(v) > 0\} \cup \{0\}$
with $\dim(W_+) > \dim(V_+)$.

Then there is $w \in W_+ \setminus \{0\}$ with $w \in V_- \oplus V_0$: $w = \sum_{j=r_++1}^n \lambda_j b_j$

$$\Rightarrow q(w) = q_B(\Phi_B(w))$$

$$= \left\langle \begin{pmatrix} 0 \\ \vdots \\ 0 \\ \lambda_{r_++1} \\ \vdots \\ \lambda_n \end{pmatrix}, \begin{pmatrix} 1 & & \\ & \ddots & \\ & & -1 & \\ & & & 0 \dots 0 \end{pmatrix} \begin{pmatrix} 0 \\ \vdots \\ 0 \\ \lambda_{r_++1} \\ \vdots \\ \lambda_n \end{pmatrix} \right\rangle \leq 0 \quad \text{!} \quad \square$$

Definition: We call $r_+ + r_-$ rank and $r_+ - r_-$ signature of the quadratic form.